



Use of remote sensing technologies in coastal mapping process

Perspectives and challenges

Sophie Loyer & Nathalie Leidinger

Shom general overview

Coastal mapping process challenged by remote sensing survey

- Lidar
- SDB
- Hyperspectral

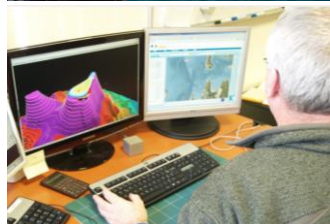
Challenges & Perspectives

A public administrative institution under the supervision of the Department of Defence



Description and prediction of the maritime and coastal environment

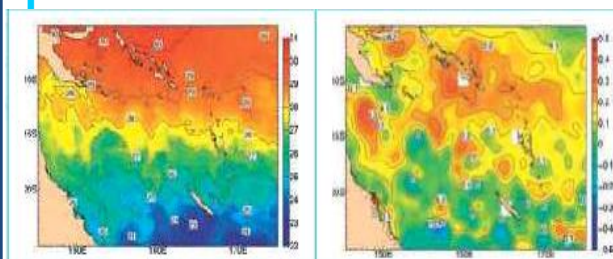
areas of expertise :
bathymetry,
sedimentology,
coastal hydrodynamics,
oceanography,
engineering of data
acquisition and
geographic information



→ to ensure **the safety of navigation**

→ to meet **Defence requirements** with regards to assessing the aero-maritime environment

→ to support **government maritime and coastal policies**



Resources

500 staff except for the crew of specialised vessels

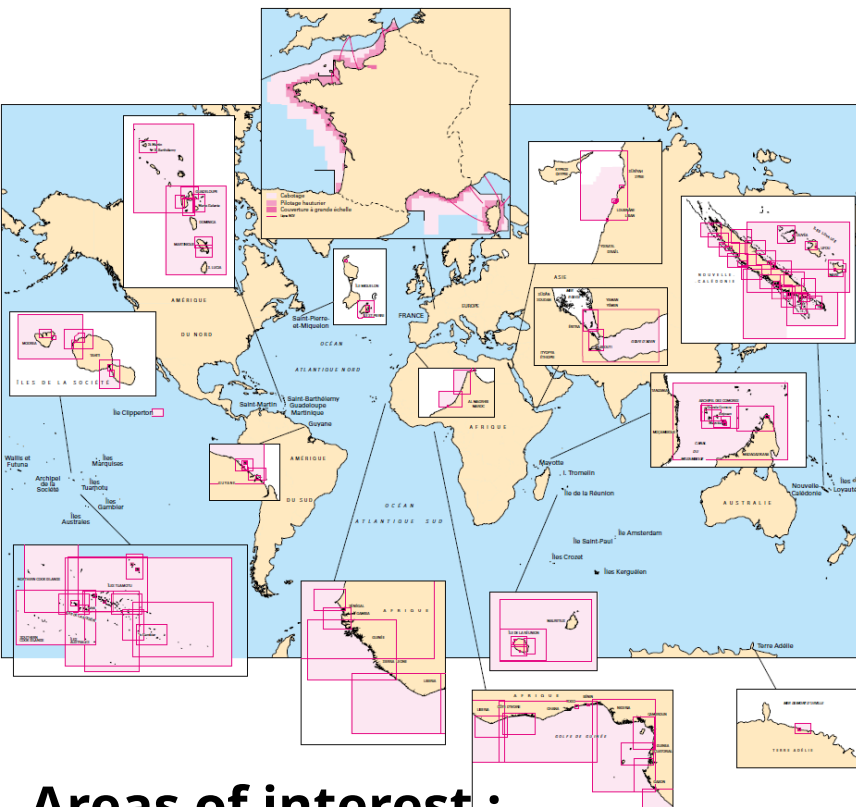
Annual budget : 58 M€ (2018)

Hydro-oceanography squadron :

- Ocean Survey *Beautemps Beupré*
Operated by Shom (95%) & Ifremer (5%)
- Ocean research *Pourquoi pas ?*
Operated by Ifremer (55%) & Shom (45%)
- Coastal Survey *Borda, Laplace, La Pérouse*



Shom ENC coverage



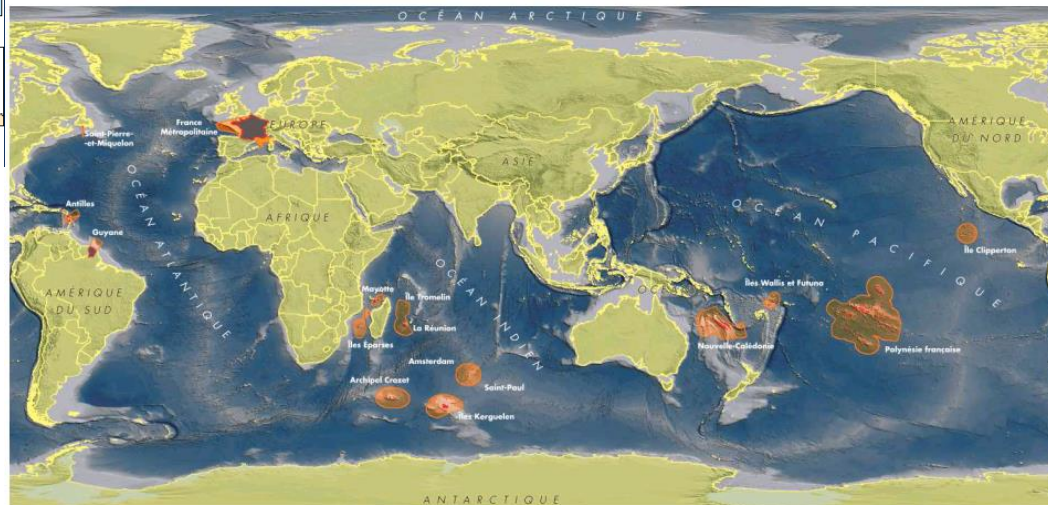
Areas of interest :

French EEZ (11 million sq. km);
and other areas of historical responsibility

NOAA's Open House on Nautical Cartography

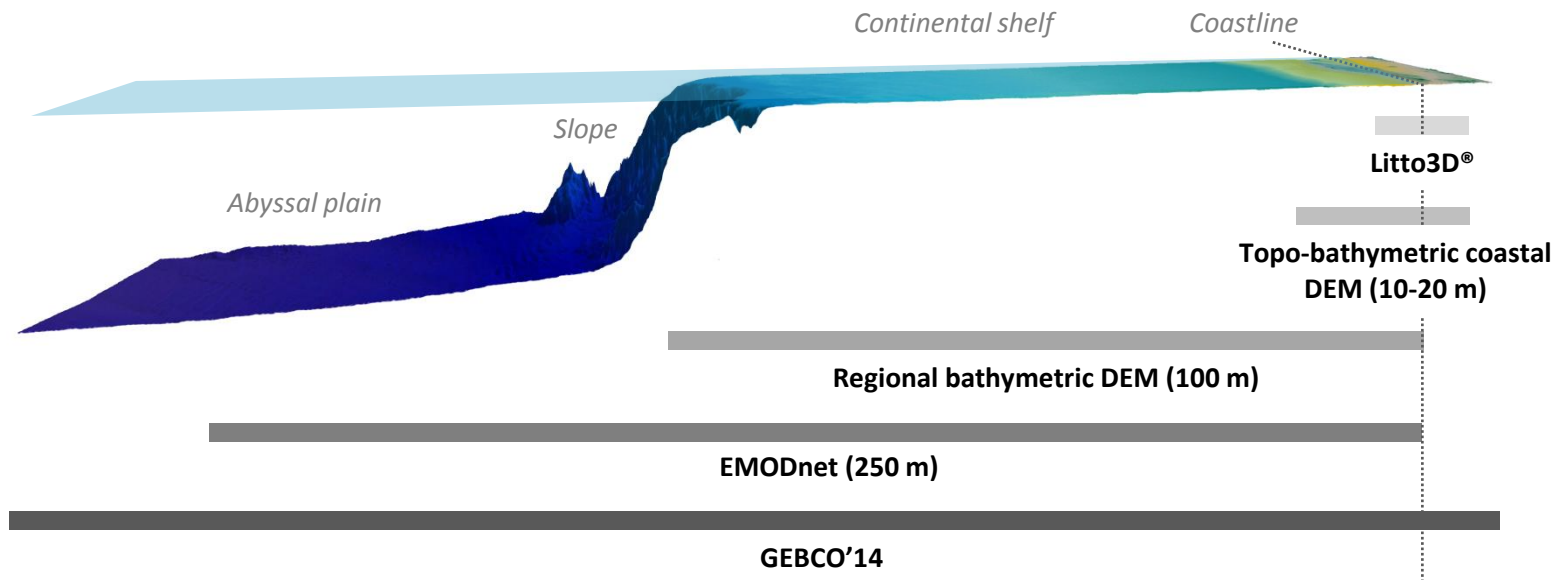
Shom chart portfolio :

- 890 paper charts (580 original charts, 260 facsimile, 50 compilation charts)
- 620 ENCs for a complete portfolio of 900 (mainland France, overseas territories and areas where France is the charting authority)



For other uses than navigation, principally:

- Hydrodynamic modelling
- Marine submersions
- Morphology, seabed characterisation
- ...

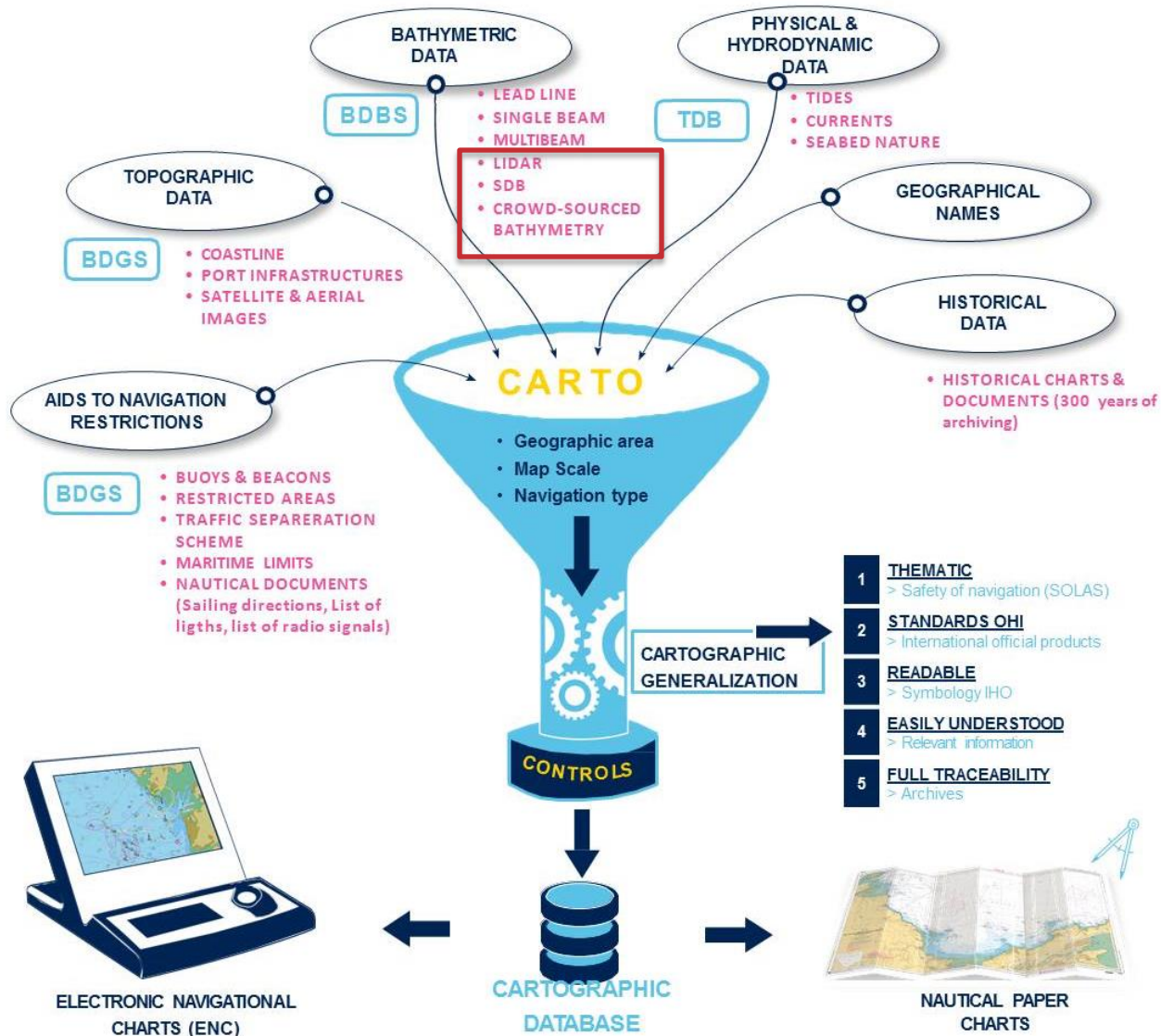


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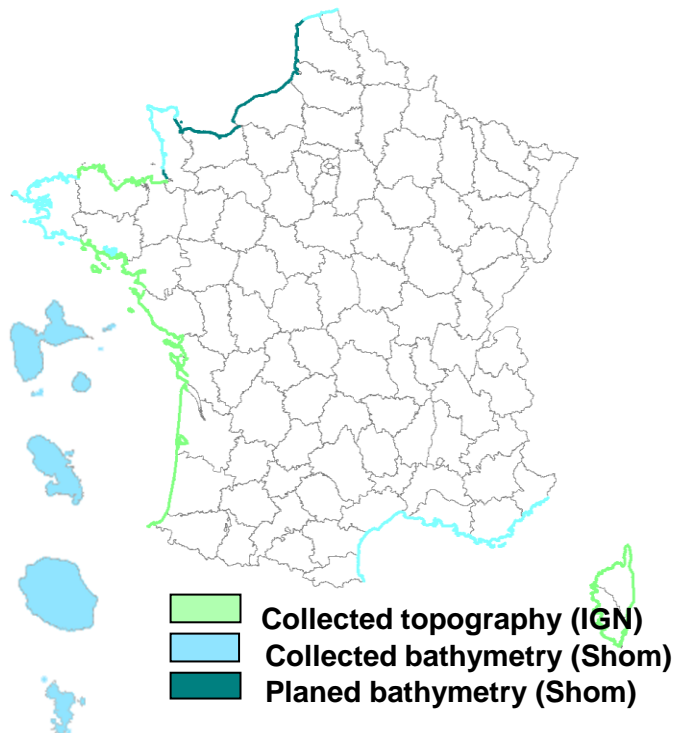
Challenges & Perspectives



AIRBORNE LIDAR BATHYMETRY

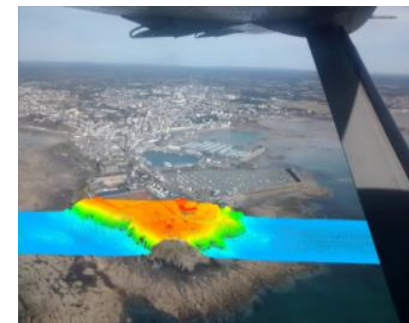


FRENCH NATIONAL PROGRAM LITTO3D® - COASTAL SURVEY



A major change in 2016 :

- “full service” contracted (at least for 3 years) with Leica Geosystems and CAE Aviation.
- Based on an ALB system = HawkEye III lidar + Cessna Grand Caravan + pilot(s) on a 2 months basis.
- Shom is in charge of the survey conduct.



In mainland France:

41% of the coastline covered

52% planned for 2018

Overseas regions :

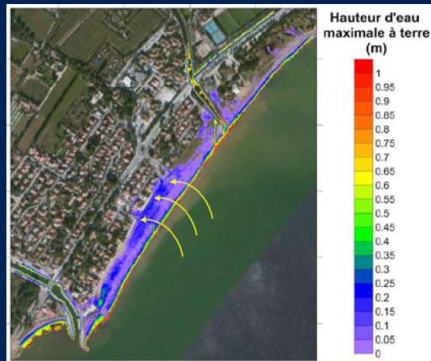
82% (excluding French Guiana)

LITTO 3D – COASTAL SURVEY

A PROGRAM TO SUPPORT GOVERNMENT POLICIES



Coastal hazards and sea level rise



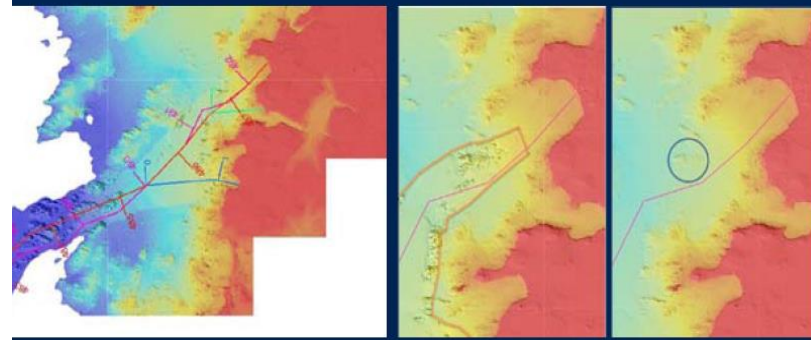
Coastline management



Management of the sedimentary stock



Marine renewable energy



And a source of nautical information to update coastal charts

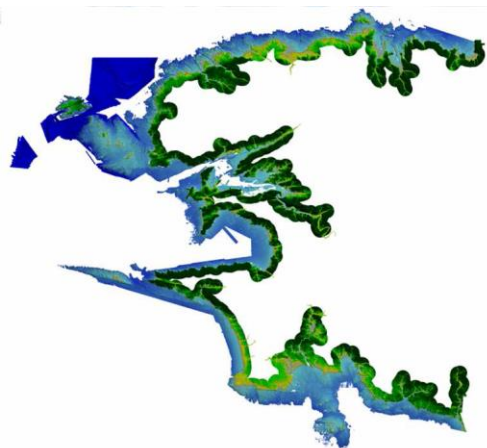
SOME RESULTS

UPDATING NAUTICAL CHARTS (1/2)

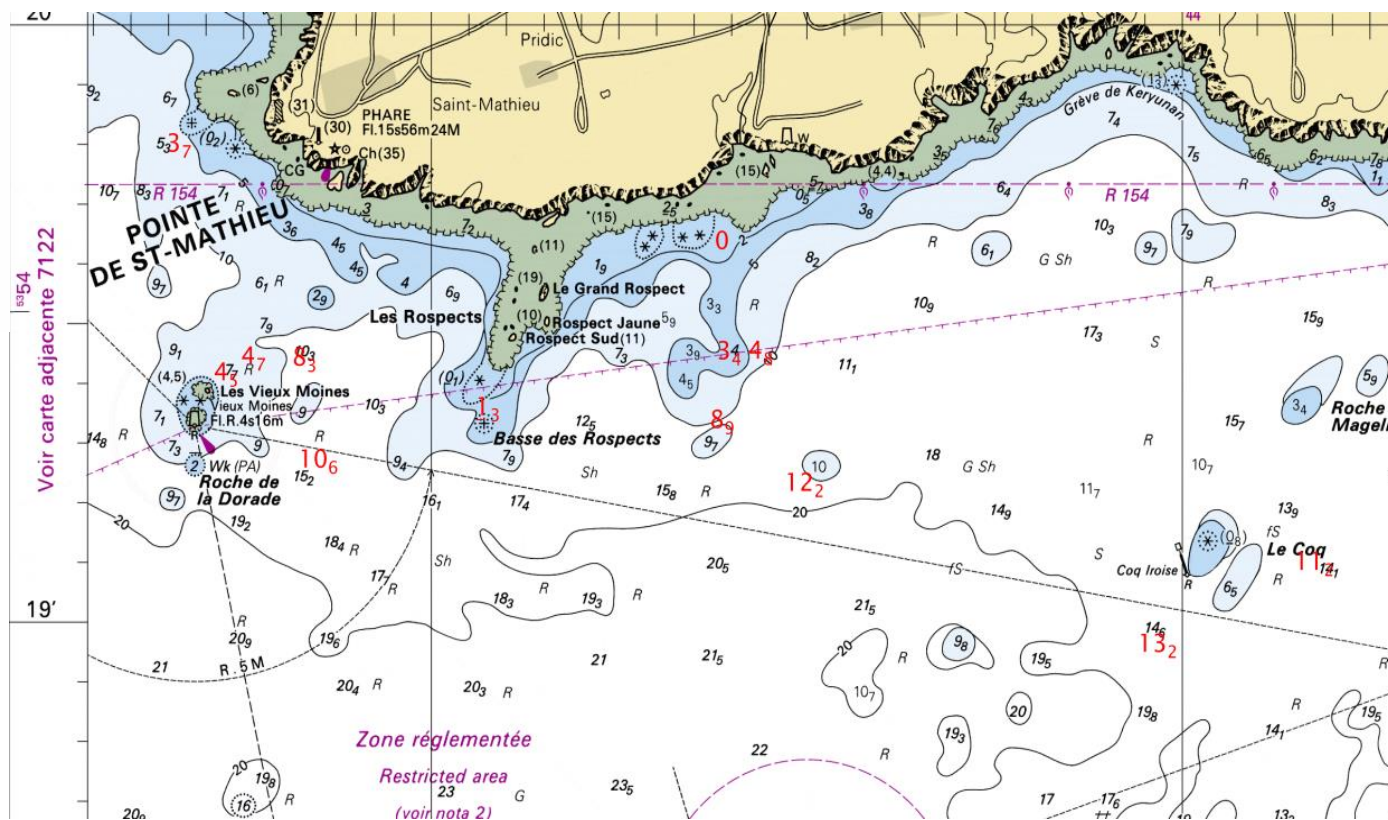


Survey « Finistère »

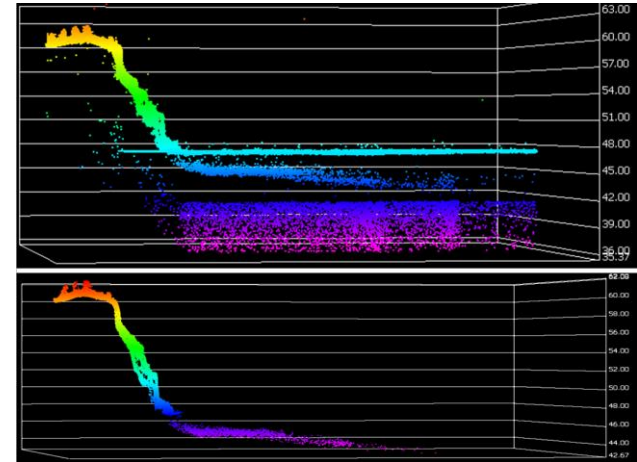
Nautical charts impacted	Total soundings	Average number of new soundings / NC
28	> 2000	~ 62



4 800 km²
1 060 km of coastline



- Lidar return is a sum of multiple echoes :
 - ➔ improve process to reduce noise,
 - ➔ move towards more automated tools instead of manual review of high-density survey
- Data Accuracy of lidar surveys is difficult to assess
- At Shom, lidar surveys always complements existing surveys

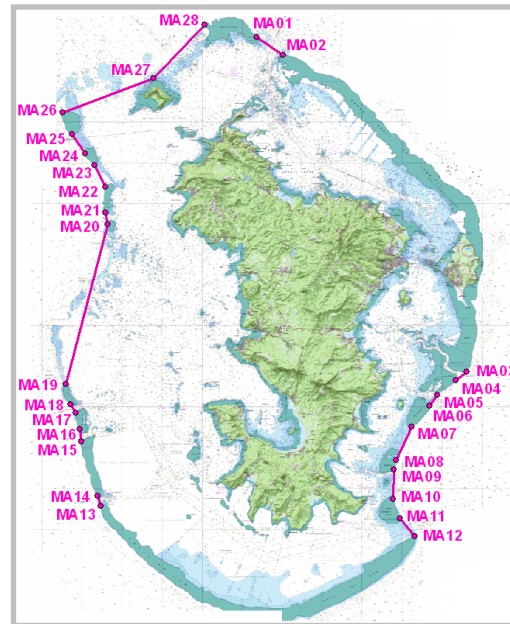
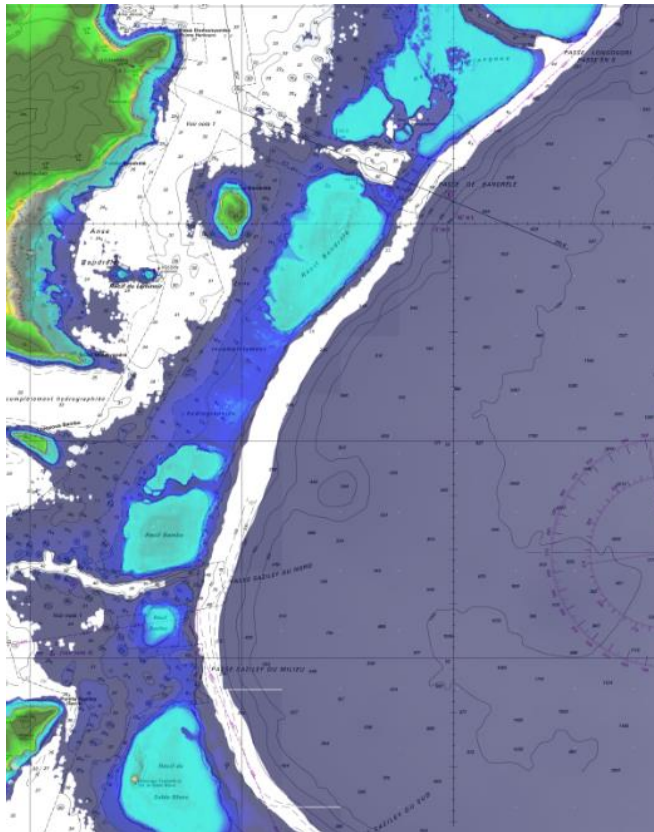


Shom cartographers used to say :
« With lidar, the most recent is not necessarily the best »

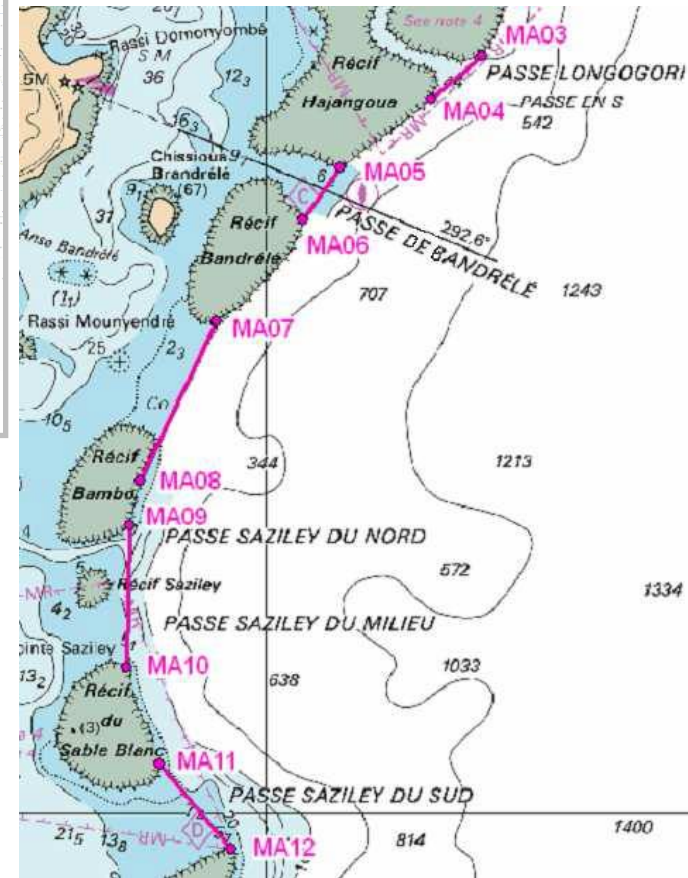
SOME RESULTS

NEW MARITIME BOUNDARY DELIMITATIONS

Exemple : Mayotte



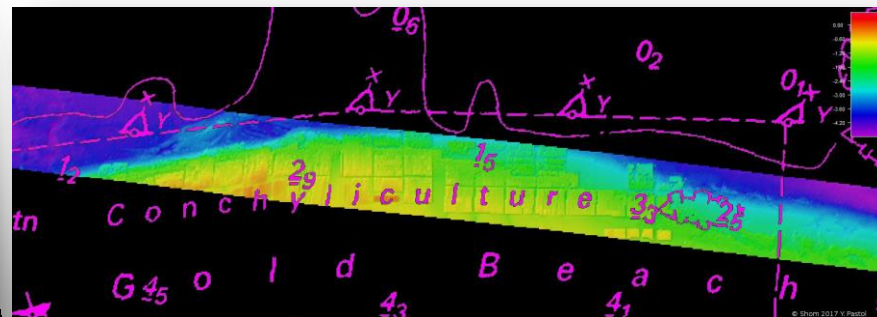
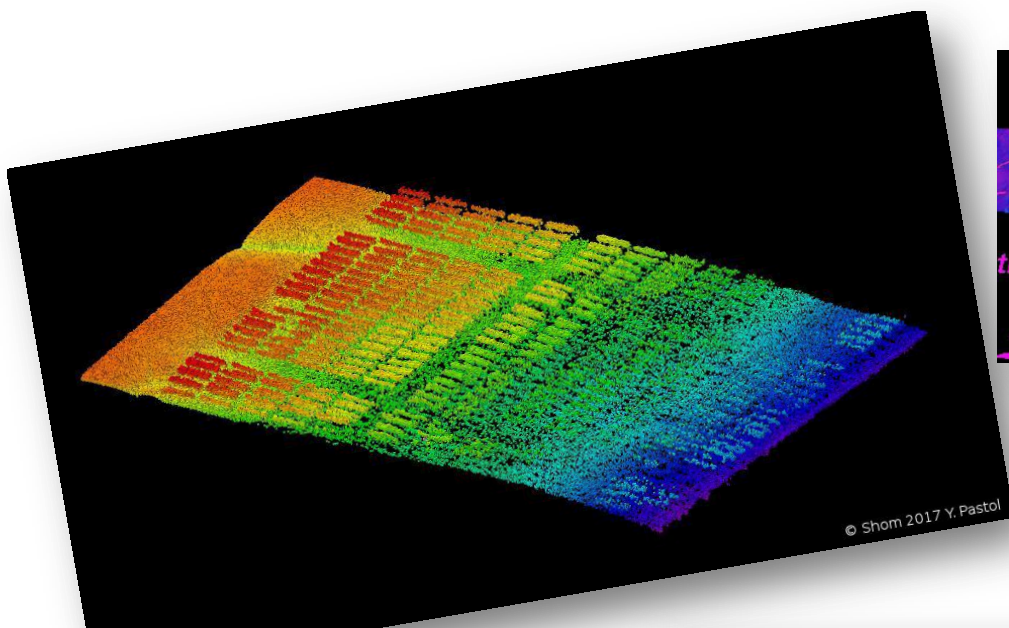
➔ Normal baseline :
intersection of
Litto3D DTM with
LAT
➔ determination of
accurate base points



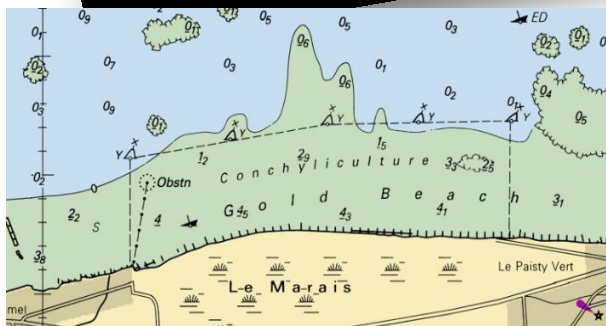
UPDATING NAUTICAL CHARTS WITH LIDAR SURVEY SOME RESULTS



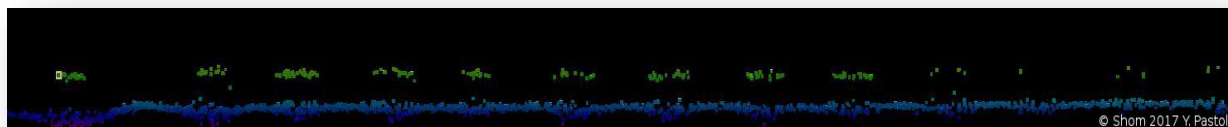
Collected lidar data for the management of shellfish parks (North of Vers-Sur-Mer)



General view



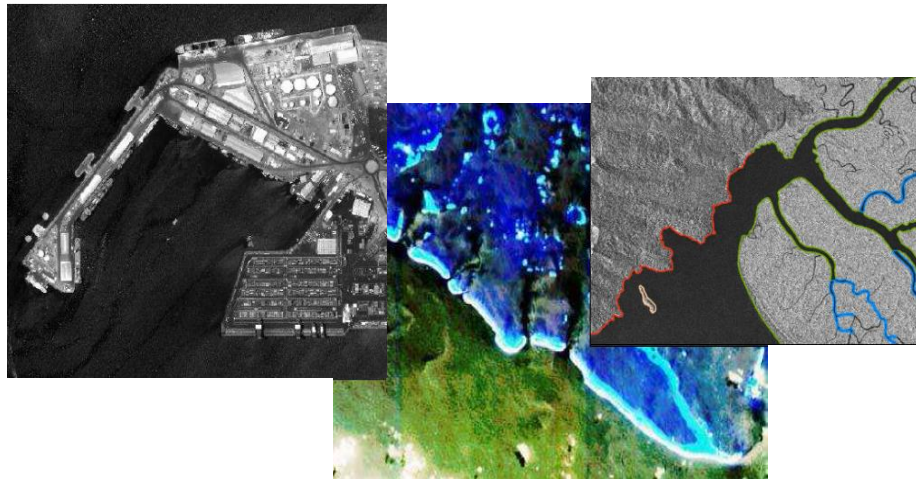
Oyster farms emerged : topographic lidar



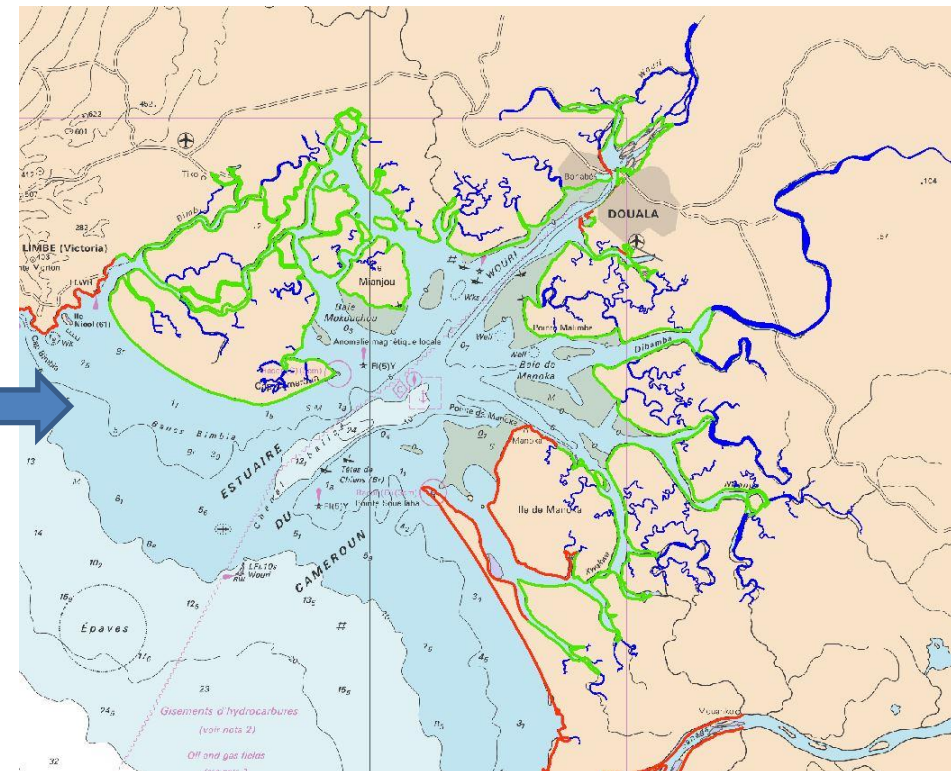
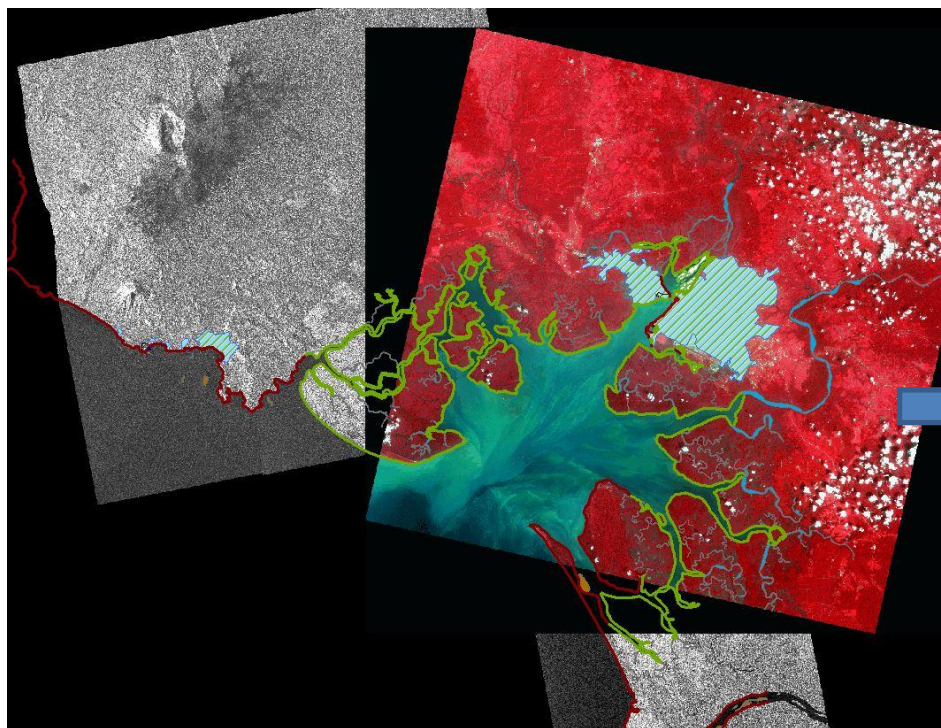
Oyster farms immersed : bathy-shallow lidar

remote sensing concerns

- ✓ Cartographic purposes :
 - To update and complete the charts with **coastal topography** and **shallow water bathymetry**
 - To update nautical informations (land informations)
- ✓ Specific Defense purposes

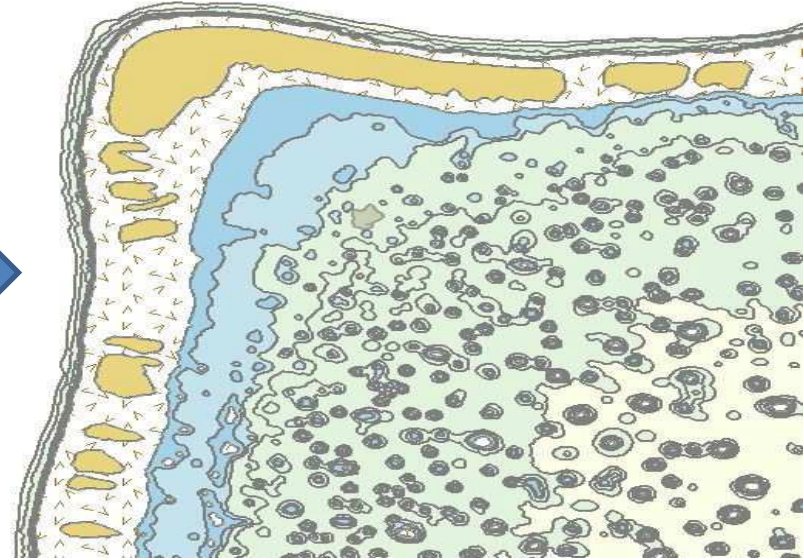


over 130 satellite derived charts (Topographic and bathymetric)

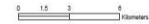


Topographic map

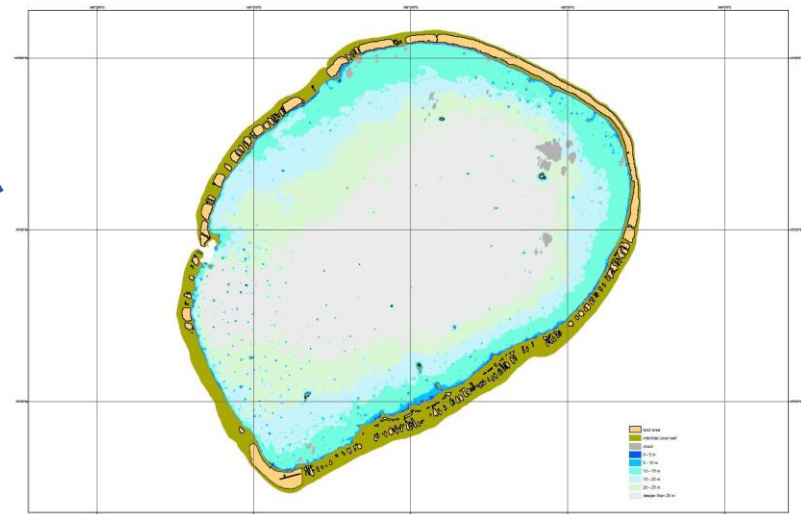
SATELLITE DERIVED BATHYMETRY => MARINE SPATIOCHART

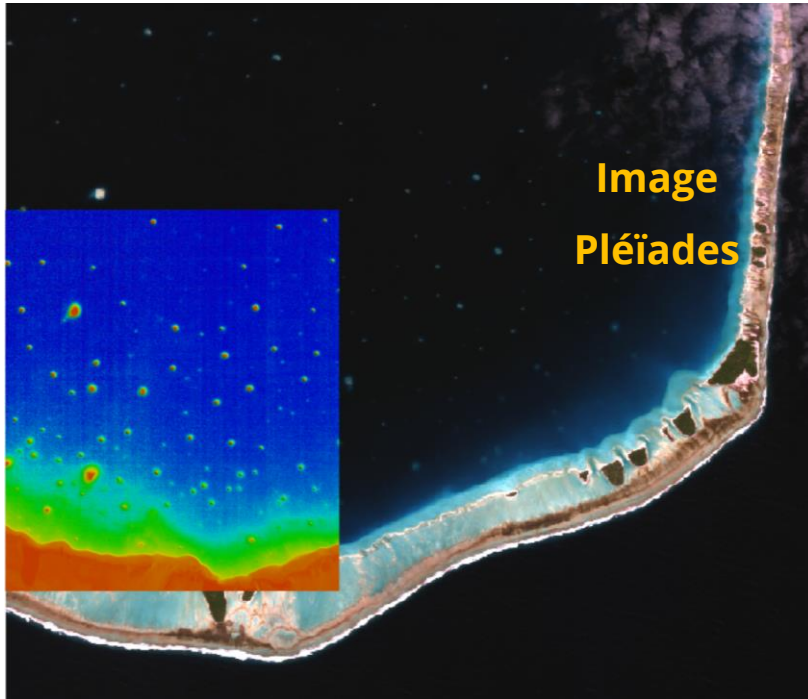


Satellite Derived Bathymetry
Tikehau atoll

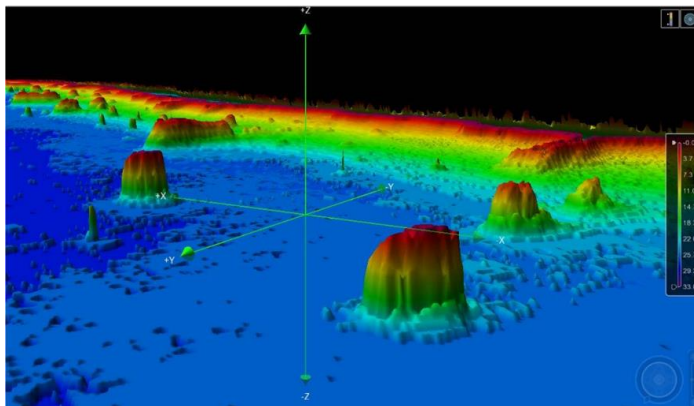
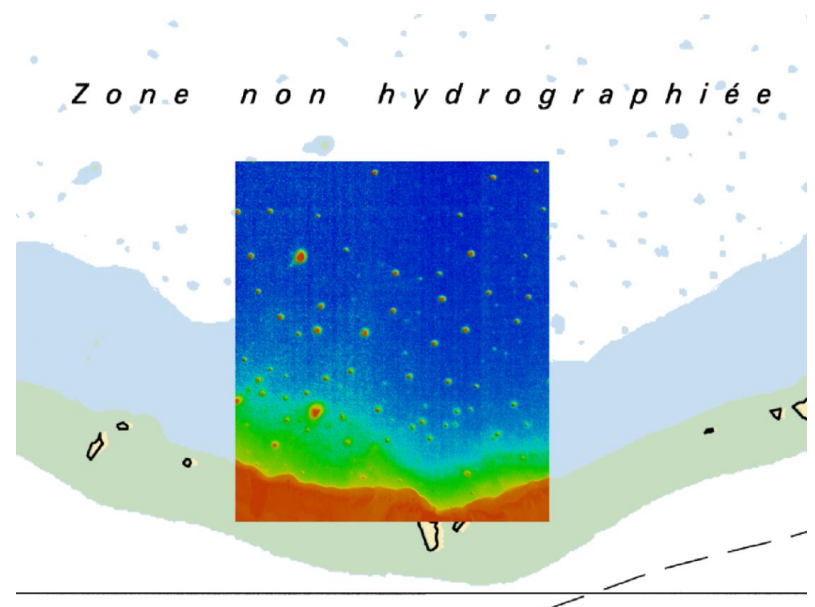


S-57 product

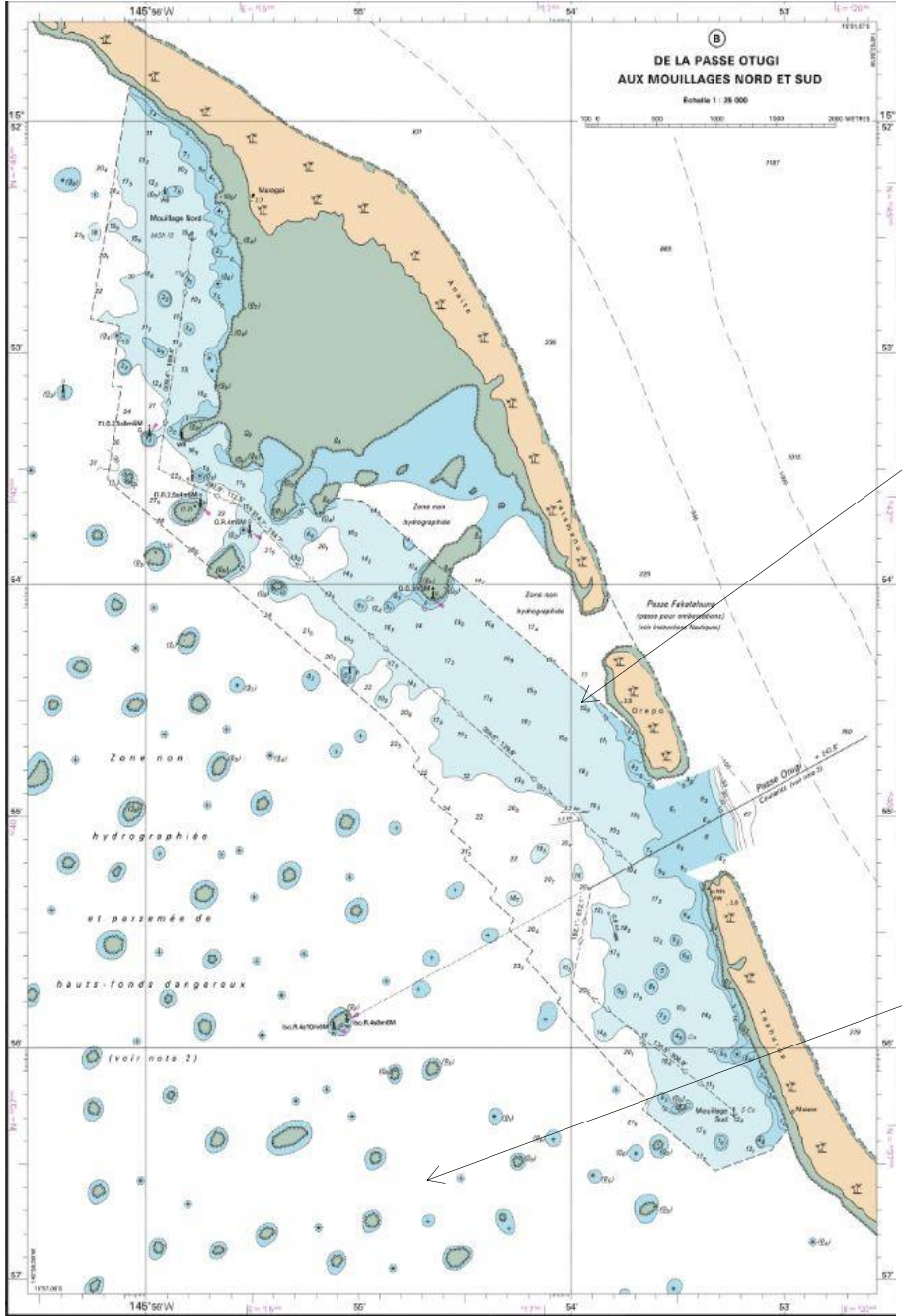




Z o n e n o n h y d r o g r a p h i é e



NOAA's Open House on Nautical Cartography



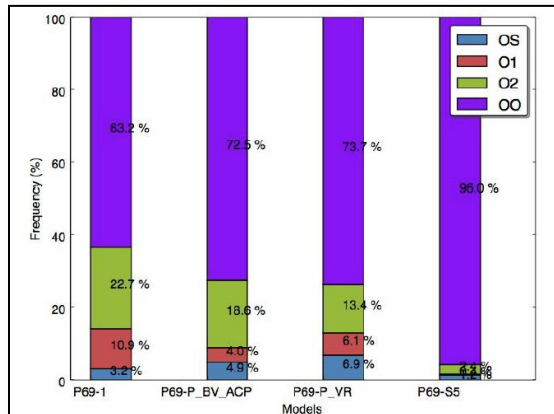
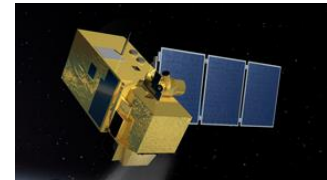
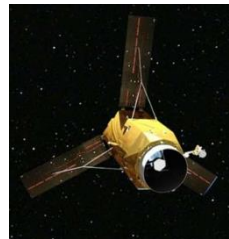
Echosounding survey

Satellite Derived Survey

NOAA's Open House on Nautical Cartography

Upgrade methodology and workflow

- Analytical physic-based modeling efficiencies (?) – no absolute requirement of in-situ data (?)
- Evaluation of the contribution of different satellite imagery sources (... cost-benefit ratio)
- Evaluation of the accuracy (vertical uncertainty) : meet standard OHI requirements



Vertical precision

- Up to 30% depth uncertainty in the [0-5m] layer
- 10% depth average uncertainty in the [5-20m] layer

Depth	Special Order	Order 1A	Order 1B	Order 2
5m (16.4')	0.25m (0.8')	0.50m (1.6')	0.50m (1.6')	1.01m (3.3')
10m (32.8')	0.26m (0.8')	0.52m (1.7')	0.52m (1.7')	1.03m (3.4')
20m (65.6')	0.29m (1.0')	0.56m (1.8)	0.56m (1.8')	1.10m (3.6')
50m (164.0')	0.49m (1.6')	0.82m (2.7')	0.82m (2.7')	1.52m (5.0')

Use of hyperspectral technology in the shallow water

Ability to collect remotely sensed bathymetric data from airborne hyperspectral imagery

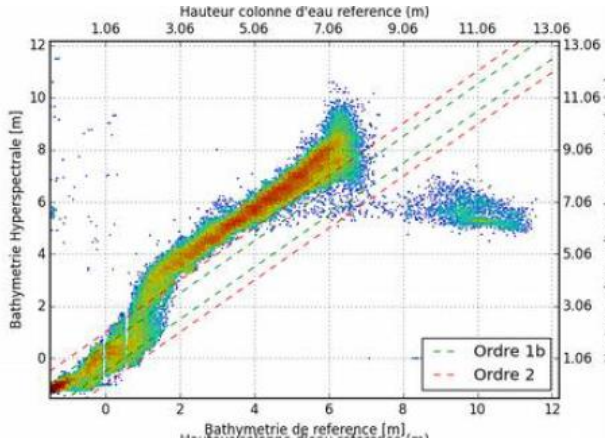
→ Study made by Hytech-Imaging to evaluate :

Capacity to obtain depth measurements that will support nautical chart : self-sufficient or must be assisted (by a bathymetric laser profiler to collect data in the center of the « swath »)?

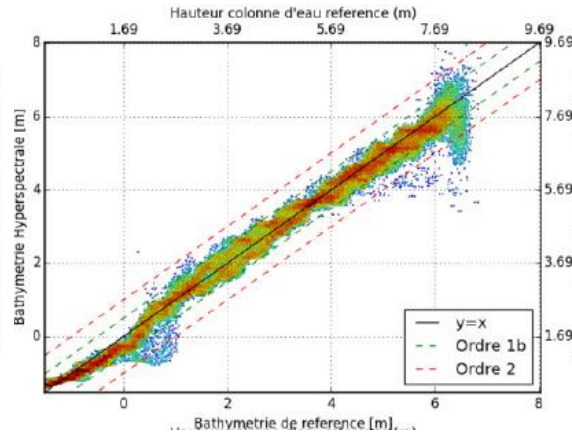
Assessment of bathymetric potential with regard to hydrography requirement ?



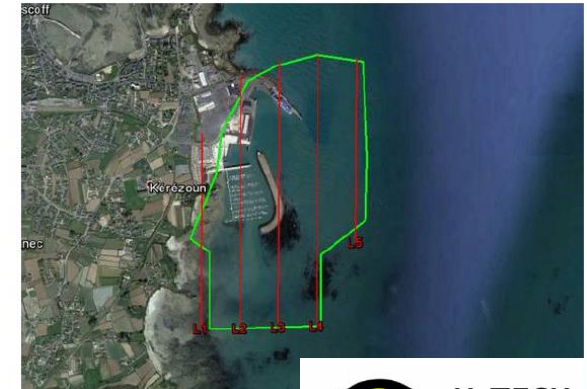
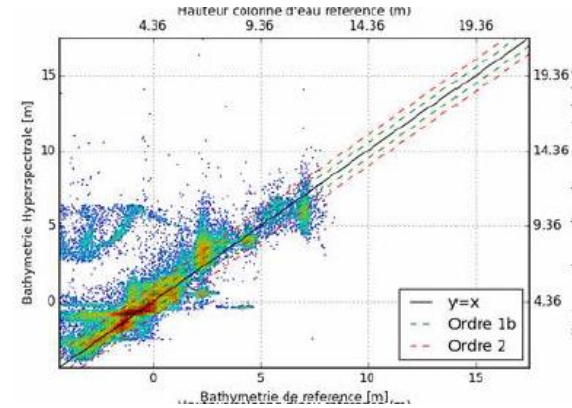
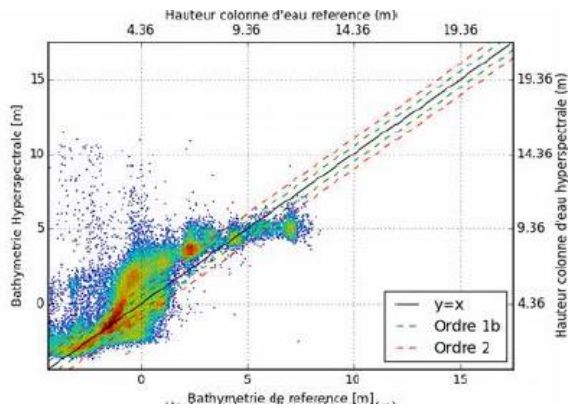
Comparative analysis of two methods : self-sufficient and assisted mode Main results in terms of bathymetric achievement



self-sufficient



assisted mode



- **Advantages**

- Great resolution (spectral and planimetric resolution)
- Powerful to remove contributions due to sea-surface sunglint, atmosphere, bottom reflectance
- IHO qualification order 2 achievable under some conditions

- **Shortcomings**

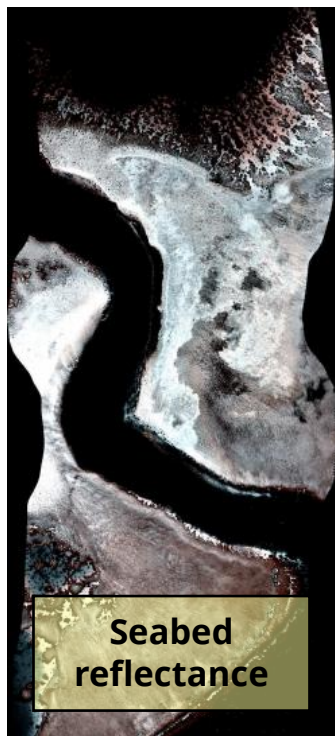
- Limited by environmental conditions
- Additional sensors have to be integrated for an operational use (bathymetric laser profiler)
- Limited to very shallow water (Order 2 : 0-7m)

- **Acquisition of a processing software workflow...**

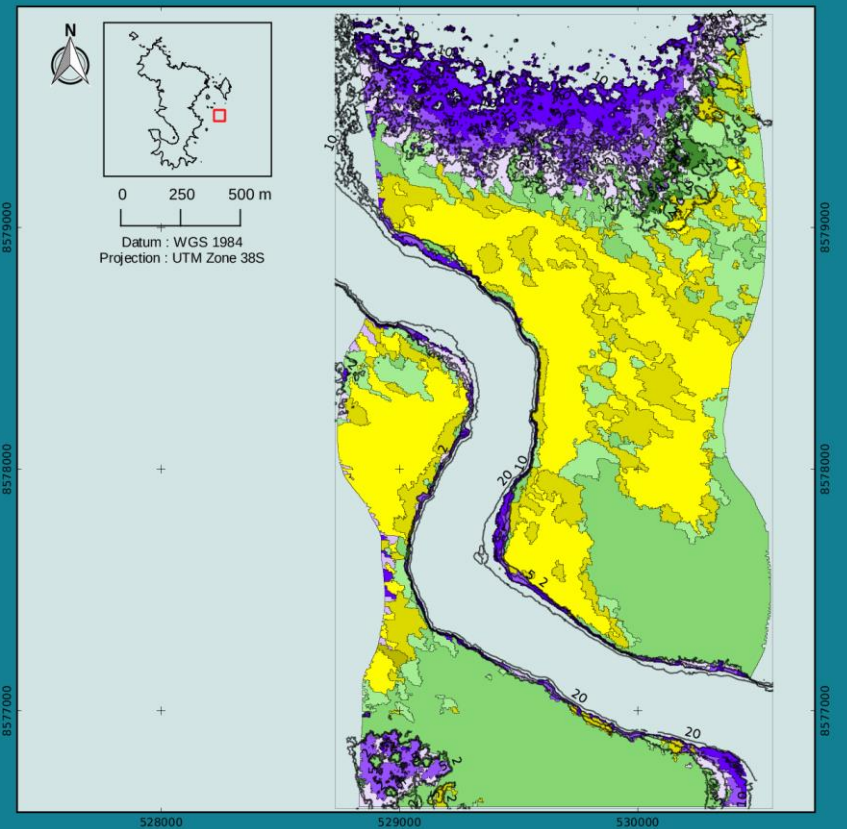
⇒ Use for environmental assessment (seafloor classification / detection of obstruction, water optics)



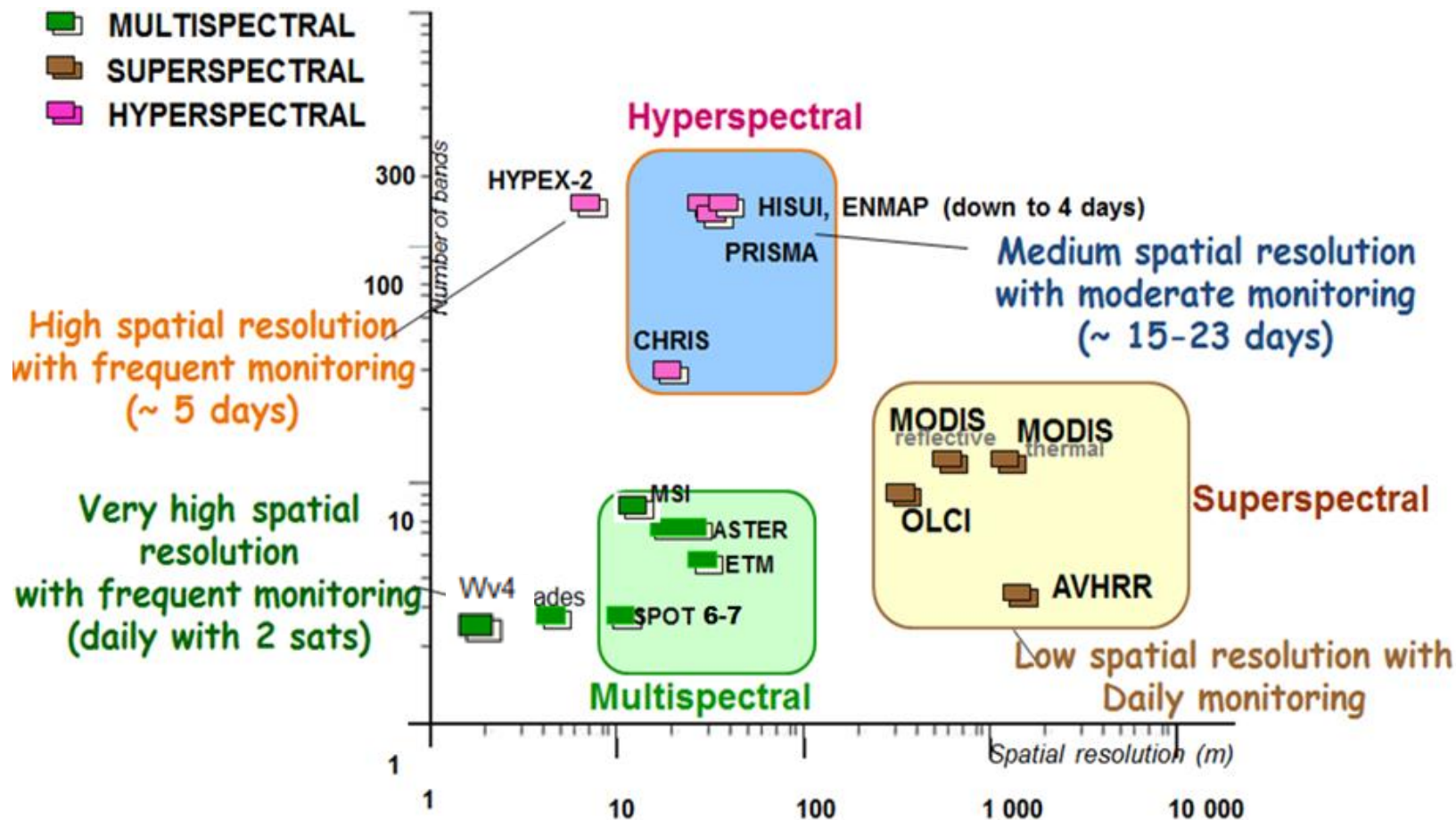
Surface reflectance



Seabed reflectance



➔ Still work to be done for a hydrographic use - but future outlooks with next generation of satellites, ...



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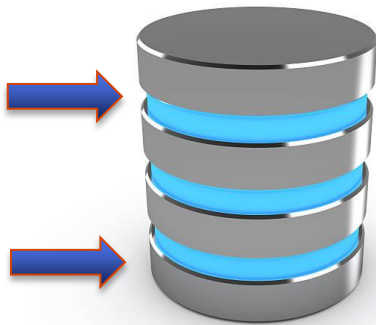
Challenges & Perspectives

Lidar, satellite derived bathymetry ... create massive amounts of data in minutes BUT it still takes weeks to derive the correct bathymetry :

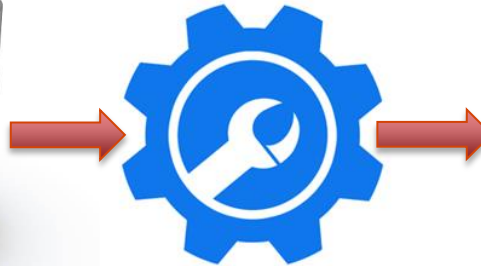
- Data volume
- Data complexity
- Data accuracy

Big data management is definitely a topic to be addressed in a better way and automated processing techniques have to be developed

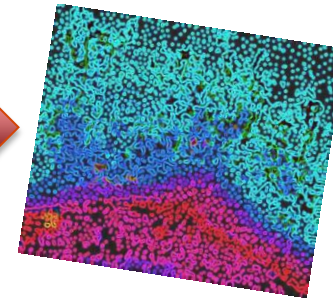
New database approach → bathymetric knowledge database / reference surface



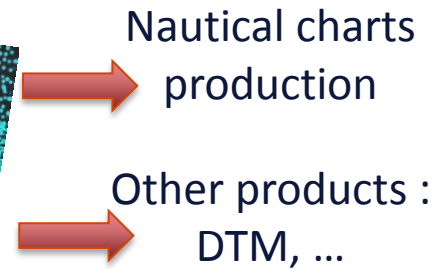
Bathymetric
DataBase (BDDBS)



Deconfliction &
Fusion tools

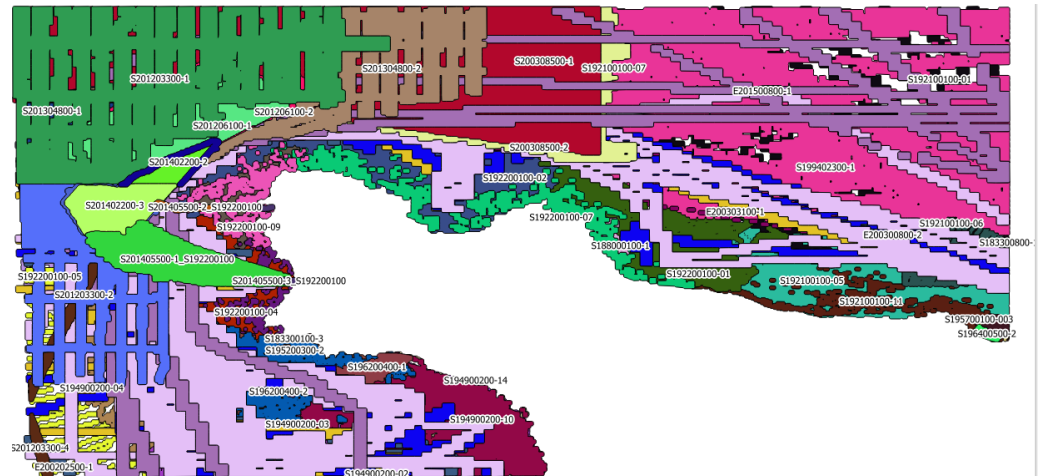
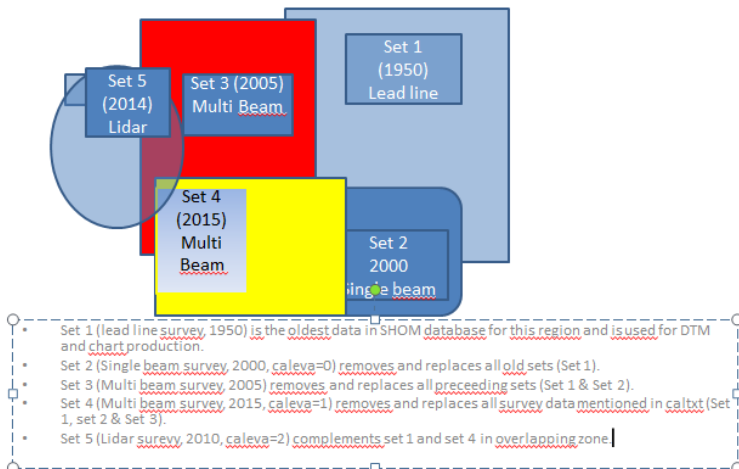


Reference surface



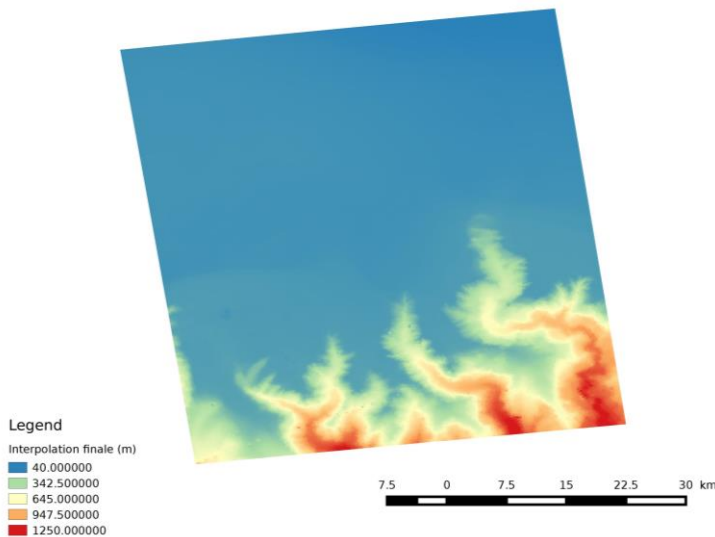
• **Deconfliction :**

- generate the « minimum surface including all the soundings of an homogeneous set in terms of hydrographic characterization »
- ➔ Relevant choice of information sources in overlapping areas

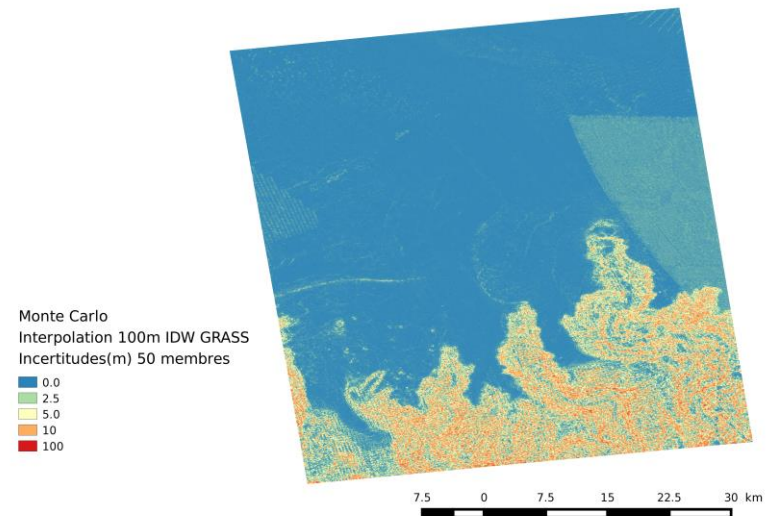


➔ Next step = test other methods of spatial indexing (Q-Tree) & take into account geospatial characteristics of data sets (density, spatial distribution, topographic variability, ...) to identify inconsistency and optimize the choice

- **Fusion, interpolation and estimation of uncertainty**
 - Interpolation nearest neighbor / spline / Kriging / Monte carlo
- ➔ Relevant strategy of interpolation and uncertainty estimation : which estimator ? For what kind of use (surface navigation ? Underwater nav ?)



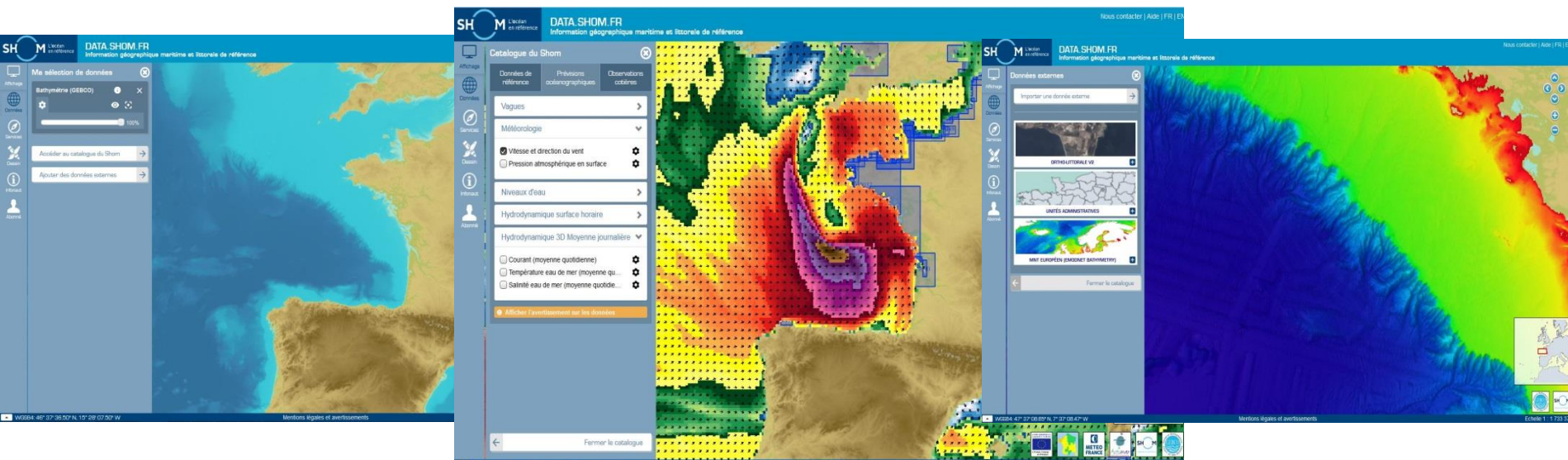
DTM generated by deterministic interpolation



Estimation of the associated uncertainty per grid node resulting from the Monte-Carlo method

- **Automation of the acquisition, processing and utilisation of the data**
 - Pydro/Hydrooffice
 - Data management (Multi-resolution grids vs point clouds, ...)
- **Data complementarity**
 - Within archived data (National/international Database)
 - Using different technologies
- **Smart data**
 - Artificial Intelligence for data processing (starting PhD Thesis « Machine learning for the optimisation of hydrographic data processing (MBES, Lidar)»)
- **Smart users**
 - Providing the user with confidence (ZOC, but also quantitatively/physically based estimation of uncertainty)
 - Chart adequacy / Resurvey strategy (SDB, CSB)

THANK YOU !



data.shom.fr → Accessing the Shom reference geospatial data for the maritime and coastal environment



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